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We regret any inconvenience this may have caused.

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Plasmonic Interferometer Array Biochip as a New Mobile Medical Device for Cancer Detection

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(Invited Paper)

Abstract—We report a plasmonic interferometer array (PIA) sensor and demonstrate its ability to detect circulating exosomal proteins in real-time with high sensitivity and low cost to enable the early detection of cancer. Specifically, a surface plasmon wave launched by the nano-groove rings interferes with the free-space light at the output of central nano-aperture and results in an intensity interference pattern. Under the single-wavelength illumination, when the target exosomal proteins are captured by antibodies bound on the surface, the biomediated change in the refractive index between the central aperture and groove rings causes the intensity change in a transmitted light. By recording the intensity changes in real-time, one can effectively screen biomolecular binding events and analyze the binding kinetics. By integrating signals from multiple sensor pairs to enhance the signal-to-noise ratio, the superior sensing resolutions of 1.63×10^{-6} refractive index unit in a refractive index change and 3.86×10^8 exosomes/mL in exosome detection were realized, respectively. Importantly, this PIA sensor can be imaged by a miniaturized microscope system coupled with a smartphone to realize a portable and highly sensitive healthcare device. The sensing resolution of 9.72×10^9 exosomes/mL in exosome detection was realized using the portable sensing system building upon a commercial smartphone.

Index Terms—Plasmonic interferometer, optical biosensor, exosome, cancer diagnosis.

I. INTRODUCTION

C ANCER is a serious socioeconomic problem. Effective screening and early detection are the only way to improve the chance of successful treatment and reduce cancer mortality. Mobile medical devices have great potential to impact the fight

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against this global health problem, especially in areas where medical resources are limited. In particular, it was estimated that approximately two-thirds of global cell-phones are actually being used in the developing world (e.g., Africa, Asia) [1]. Therefore, sensitive biomedical devices integrated with smartphones would yield promising mobile medical devices for cancer screening and early detection and introduce great impact on point-of-care diagnostics in developing countries and resourcelimited areas.

Surface plasmons (SPs) are coherent oscillations of conduction electrons on a metal surface excited by electromagnetic radiation at the metal-dielectric interface [2]. The extremely high sensitivity of the surface plasmon resonance (SPR) to the refractive index (RI) change on the metal surface has led to the development of SPR sensing systems, which typically use prisms to couple obliquely incident light into SP waves propagating on a flat, continuous metal film (typically gold) [3]. However, the conventional SPR systems are limited by expensive equipment and bulky footprint. Therefore, they are not suitable for cost-effective, point-of-care diagnostic tests. To overcome these challenges, nanoplasmonic biosensors have received significant attentions as attractive miniaturized platforms for sensitive, label-free and high throughput detection of bio-chemical analytes. The most popular nanoplasmonic sensor architectures studied in recent years are metallic nanohole or nanopattern arrays (e.g., [4]–[8]). However, instead of further improving the sensing limit, recent major efforts have mainly focused on the integration of nanoplasmonic sensing elements with different sensing systems to enable more portable sensing applications. For instance, a nanohole array plasmonic biosensor was integrated with the smart-phone microscope and resolved a 3-nm-thick monolayer of bovine serum albumin (BSA) molecules (corresponding to the surface coverage sensitivity of $\sim 4 \text{ ng/mm}^2$) [9]. More recently, researchers developed a nanoplasmonic exosome (nPLEX) assay to analyze ascites samples from ovarian cancer patients [10]. The nPLEX assay used exosomal CD24 and EpCAM as the biomarkers and discriminated ovarian cancer patients from noncancerous cirrhosis patients with high accuracy, demonstrating its potential for exosome based cancer diagnostics [11]. Since the target cancer biomarker (i.e., exosomes) are $50 \sim 100$ -nm-sized nanoparticle, it does not require record-breaking sensitivity to resolve their binding events on sensor surface. For these applications, the

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key target is the integration of plasmonic nanostructures with low-cost experimental settings to realize high performance sensing. However, most previously reported plasmonic sensing devices are based on wavelength modulation (e.g., [4]–[8]). Therefore, high spatial density multiplexed measurements are difficult to achieve in that broadband wavelength analysis because a spectrometer is required, which inevitably adds to the size and cost of the entire system.

We previously developed a plasmonic interferometer array (PIA) biosensor based on wavelength modulation generated by ring-hole nanostructures. Using this type PIA biosensor, the sensitive detection of BSA surface coverage as low as 0.4 pg mm^{-2} was realized [12]. In this study, we have further developed the PIA biosensor using intensity modulation at a single wavelength by optimizing the geometry of the ring-hole nanostructure. These new designs allow us to monitor the intensity change from each sensor unit, which enables superior detection sensitivity but requires neither spectrometer nor angle-tunable prism-coupling system, leading to a significant reduction in device cost and instrumental complexity. We have also integrated the PIA biosensor in an optofluidic biochip and attached to the imaging system of a smart-phone for general portable biosensing.

II. SENSOR DESIGN AND FABRICATION

Fig. 1(a) illustrates the ring-hole plasmonic interferometer structure with a nanohole in a metal film surrounded by concentric circular nanogrooves. When the incident light illuminates the structure at the normal direction, SP waves are launched at the grooves. They will propagate along the radial direction of the rings towards the central nanohole and interfere with the directly-transmitted light through the central nanohole (see Fig. 1(b) for the cross-sectional diagram). In this case, the transmitted light intensity at a given wavelength, λ , through the plasmonic interferometer can be described as:

$$I_t = I_{free} + I_{sp} + 2\sqrt{I_{free}I_{sp}}\cos\left(\frac{2\pi R}{\lambda}n_{sp} + \varphi_0\right) \quad (1)$$

where $I_{\rm free}$ and $I_{\rm sp}$ are intensities of the free-space and SPmediated light, respectively. The cosine term represents the interference between these two components. Here R is the radius of the circular ring; λ is incident wavelength; $n_{\rm sp} =$ $\operatorname{Re}[(\varepsilon_{\rm m}n^2/(\varepsilon_{\rm m}+n^2))^{1/2}]$ represents the effective RI for SPs at the metal/dielectric interface, where $\varepsilon_{\rm m}$ is the metal permittivity, n is the RI of the dielectric medium on top of the metal surface; φ_0 is an additional phase shift introduced during the SP coupling process at the nanogroove [13]. According to this equation, the transmitted light intensity I_t at a given λ can be modulated by R and n_{sp} .

To demonstrate the intensity-modulated biosensor, we used Focused Ion Beam (FIB) milling to fabricate a 5 \times 5 array of ring-hole plasmonic interferometers on a 250-nm gold film that was deposited on a glass substrate with 5-nm titanium adhesion layer in between. As we can see from its SEM image shown in Fig. 1(c), the diameter of the ring, *R*, increases from 4.07 μ m to 4.75 μ m with the step size of ~28 nm. According to our previous investigation [14], the efficiency of a single nanogroove to couple normally-incident free-space light at λ into SPs depends on its width (w) and depth (d). By optimizing these two parameters in numerical modeling and calculating the theoretical SP coupling efficiency, we selected a set of parameters for nanofabrication (i.e., w = 240 nm and depth d = 70 nm). To further enhance the coupled-SP intensity, three grooves were selected in this experiment with the groove period P = 480 nm, which was designed to match with the effective wavelength of SPs (i.e., $\lambda_{sp} = n_{sp}\lambda$) under water environment so that SPs generated at each groove are tuned in phase. The diameter of the central hole was tuned to 620 nm to control the directly transmitted light intensity to match the SP-intensity and maximize the interference contrast. The center-to-center distance between two adjacent elements along x and y direction are both 12.5 μ m. In our optical characterization, a collimated LED source (Thorlabs M660L3-C1, operated at 800 mW) was passed through a laser line filter (Thorlabs FL670-10) to get a narrow-band red light with a centered wavelength $\lambda = 665$ nm and a linewidth of \sim 7-nm, which was employed to illuminate fabricated PIA sample at the normal direction. The transmitted image of the sensor array was collected by a 40X objective lens (NA = 0.6) and imaged using a CCD camera (Hamamatsu C8484-03G02). The camera exposure time was set as 160 ms and the capture rate was 37 frames/min. As a result, one can see from Fig. 1(d) that the transmitted intensity of each interferometer unit was modulated by R when n is fixed at ~ 1.33 (i.e., water environment under room temperature).

To calibrate the sensing performance, a PDMS-based microfluidic channel was bonded on the sensor chip to introduce glycerol-water solutions with different concentrations to control the bulk RI (Fig. 1(e)). When the water is injected into the microfluidic channel, each element shows different brightness, demonstrating the intensity interference at a single wavelength transmitted through the array as the function of R. As shown in Fig. 1(f), the extracted intensity is normalized by the transmitted light intensity through a reference hole without grooves, showing an interference period of ~ 490 nm, very close to λ_{sp} and therefore verifying the interference mechanism. As the RI increases, the transmitted intensity from each sensing element will either increase or decrease. The highest sensitivity among these sensing elements can be obtained at the waist of the interference pattern as indicated by the two black dashed lines in Fig. 1(f), which are $8.8 \times 10^3 \%$ /RIU and $-6.7 \times 10^3 \%$ /RIU, respectively. This intensity-modulated sensitivity obtained from a single plasmonic interferometer is equivalent to the best results obtained by intensity-modulated nanohole arrays based on dual-polarization responses [15].

To enhance the sensor performance, we then fabricated these two most sensitive interferometers (i.e., $R_1 = 4.25 \ \mu m$ and $R_2 = 4.50 \ \mu m$) as an 8 × 8 "chessboard" array (see Fig. 2(a) for its SEM image). Real-time responses of all interferometer units in the array are plotted in Fig. 2(b). In this experiment, different solution samples were used to tune the bulk refractive index. The refractive indices of the deionized water and a series of glycerol-water solutions (i.e., 3%, 6%, and 9% glycerol solutions) are 1.3328, 1.3370, 1.3419, and 1.3463, respectively



Fig. 1. (a) Schematic of a ring-hole plasmonic interferometer. (b) Cross-section view. (c) SEM image of a 5X5 array of plasmonic interferometer with increasing *R* from left to right, bottom to top. (d) Transmitted light of the interferometer array was imaged on the CCD camera. (e) Schematic diagram of the experimental setup. (f) Transmission of each interferometer was modulated sinusoidally by *R*, showing different sensitivity when glycerol-water solutions of increased concentrations were flowed on the sensor surface. Black arrows indicate the interferometers with highest sensitivities.



Fig. 2. (a) SEM image of an 8×8 "chessboard" array of ring-hole plasmonic interferometers with two different radius ($R_1 = 4.25 \ \mu m$ and $R_2 = 4.5 \ \mu m$). Scale bar: 10 μ m. (b) Real-time transmission signals of each interferometer in the array in response to different concentrations of glycerol-water solutions flowing on the metal surface. (c) Differential signal of 32 pairs of neighboring interferometers. (d) Enumeration of sensor resolution of each pair of neighboring interferometers. Their mean value and standard deviation are represented by *m* and σ , respectively. (e) Sensor resolution can be improved by averaging signals of multiple sensor pairs. (f) Real-time transmission response by averaging signals of all 32 sensor pairs.

(characterized using Reichert, Part #13940014). One can see that the interferometers with two selected radius showed opposite response to the bulk RI change on the sensor surface. As the RI increases on the sensor surface, the transmitted intensity of the R_1 sensor unit increases, while the intensity of the R_2 sensor unit decreases at the same time. Therefore, any horizontally or vertically adjacent two interferometers can work as a sensor pair (see red dashed squares i Fig. 2(a)). Since adjacent sensor units are spatially close to each other, they should share a similar background signal introduced by inevitable fluctuations in the microfluidic channel (e.g., localized light intensity fluctuation, environment temperature variation, system mechanical vibrations, etc.) [16]. Using this self-reference strategy, the background signal change can easily be removed by calculating their differential signal. For instance, here we consider every two horizontally adjacent interferometers as a sensor pair. The differential signals of 32 sensing pairs are plotted in Fig. 2(c). By subtracting the decreasing R_2 signal from the increasing R_1 signal, the signal changes from these two sensor units were added up. Importantly, the background noise was removed, resulting in a higher signal-to-noise ratio (SNR). As shown in Fig. 2(d), we calculated the resolution of the 32 sensor pairs, showing great repeatability in the range of $4.2 \sim 6.3 \times 10^{-6}$ RIU (with the mean value, *m*, of 5.50×10^{-6} RIU and the standard deviation, σ , of 5.37×10^{-7} RIU). This resolution is better than previously-reported best nanoplasmonic biosensors based on intensity modulation [15], [17]–[19].

Moreover, by averaging signals of all 32 sensor pairs, the noise can be reduced and hence the sensor resolution can be optimized further. As shown in Fig. 2(e), we plot the sensor resolution versus the number of sensor pairs used in the signal averaging process (i.e., 1 to 32), showing that the overall sensing resolution can be reduced to $\sim 1.63 \times 10^{-6}$ RIU. The averaged signal of all 32 sensor pairs is shown in Fig. 2(f), demonstrating a much better SNR compared with the original data shown in Fig. 2(b). Remarkably, this RI sensing resolution is already comparable to those of the best commercial SPR imaging systems $(2-5 \times 10^{-6} \text{ RIU})$ [20], [21]. By employing higher performance light sources and CCD cameras with lower noise, this performance can be improved further. On the other hand, instead of competing the sensing limit, recent major efforts have mainly focused on the development of portable optical biosensing systems by integrating nanoplasmonic sensing elements with miniaturized optical components (e.g., [9], [22]). Next, we will integrate the PIA sensor with an optofluidic biochip and show the feasibility of using the PIA biochip to detect circulating biomarkers in blood for cancer diagnosis.

III. REAL-TIME DETECTION OF EXOSOMAL EGFR USING THE PIA BIOCHIP

To demonstrate the potential of the PIA biochip as a mobile medical device for disease diagnosis, we selected lung cancer as the disease model, which is the leading cause of cancer-deaths around the world [23], and exosomal EGFR (epidermal growth factor receptor) as the biomarker. Exosomes are nano-sized (50–100 nm) extracellular vesicles secreted by many cell types under normal physiological conditions and exist widely in a variety of body fluids, such as blood and urine [24], [25]. Exosomes transfer DNA, RNA, micro-RNA, proteins and lipids from parent cells to recipient cells, and serve as "messengers" for cell-cell communication [26]. Exosomes are actively involved in cancer development, metastasis, and drug resistance [27]; therefore, they are promising cancer biomarkers for non-invasive, in vitro diagnostics. For examples, exosomal glypican-1 detected early stages of pancreatic cancer with 100% sensitivity and specificity [28]. Here we selected exosomal EGFR as the biomarker for lung cancer detection because EGFR is a lung cancer driver gene and regulates cancer cell proliferation and survival [29]. Recent studies indicate that the expression of exosomal EGFR is significantly dysregulated in plasma samples from lung cancer patients [30], [31] and is closely correlated with lung cancer patients' overall survival rate [32], indicating the promising value of exosomal EGFR in lung cancer diagnosis and prognosis.



Fig. 3. (a) Schematic diagram of the developed ring-hole PIA biochip with captured EGFR+ exosomes. (b) Real-time response of 18-pair sensing units upon exosome adsorption on the sensor surface. (c-d) SEM images of the sensor surface (c) before and (d) after exosome binding. Scale bar: $2 \mu m$. Red squares indicate obvious exosome binding within the ring area after exosome binding.

To demonstrate the feasibility of using the PIA biochip for cancer diagnosis, we first used a desktop microscope (Olympus IX81) to measure the expression of EGFR on the exosomes derived from A549 non-small cell lung cancer cells. To enable the sensing of exosomal EGFR, anti-EGFR antibodies were conjugated on the surface through a series of surface modification steps. As shown in Fig. 3(a), a mixture of PEG200-SH and biotin-PEG-1000-SH (1:3 molar ratio, 10mM in PBS) was first applied on the surface of gold nanostructures for 1 hour. After washing off unbound PEG, 5 ng/mL NeutrAvidin was added and incubated on the biochip for 1 hour. Then the extra NeutrAvidin was removed by PBS washing. Finally, 0.05 mg/mL biotinylated anti-EGFR antibodies were applied and incubated on the biochip for 1 hour to allow the binding of antibodies on the surface through biotin-avidin interaction. After the removal of excess antibodies by PBS washing, the PIA biochip was ready for use. All the modification steps were performed at room temperature.

To measure the level of exosomal EGFR, deionized-H₂O (Di-H₂O) and PBS solutions were fed through the PIA biochip at 0.02 mL/min for 10 minutes each to collect the baseline signals $(I_{water} \text{ and } I_{PBS})$. As shown in Fig. 3(b), the transmission signal intensity increased after PBS solution injection due to the RI change (i.e., from Water 1.3328 to PBS 1.3343). The exosomes derived from A549 cells were suspended in PBS buffer at the concentration of 2×10^{10} exosomes/mL, and introduced into the PIA biochip at a flow rate of 0.02 mL/min. A quick increase of the signal intensity was observed right after the exosomes entered the PIA biochip. Then the signal intensity leveled off and reached plateau at time of 3×10^3 seconds. The dynamic change of the transmission signal intensity demonstrated the successful capture of exosomes via anti-EGFR antibodies on the biochip. Finally, PBS was flowed through the PIA biochip at 0.02 mL/min for 10 min to wash off all non-specifically bound

exosomes. The transmission signal intensity after PBS wash was recorded as $I_{exosome}$. The expression (E) of exosomal EGFR observed in this PIA biochip was 0.21, which was calculated using the following equation (2). The PIA biochip showed a high detection sensitivity with the SNR of 51.76, corresponding to the resolution of 3.86×10^8 exosomes/mL.

$$E = \frac{I_{exosome} - I_{PBS}}{I_{PBS} - I_{water}}$$
(2)

To further demonstrate the capture of exosomes by the anti-EGFR antibodies on the biochip, we took the SEM images of the biochip surface before and after exosome binding. As shown in Fig. 3(c) and (d), a number of exosomes were observed around the ring-hole nanostructures as indicated by the red dotted rectangles. The sensitive detection of lung cancer cell-derived exosomal EGFR with high SNR indicated the potential application of the PIA biochip in exosome-based cancer diagnosis. It is important to note that our sensor footprint (70 μ m \times 70 μ m) is around two orders of magnitude smaller than that of commercial prism-based SPR systems. This largely improved sensor resolution per unit area facilitates sensor integration with compact microfluidics and also decreases the sample consumption. Furthermore, the collinear transmission setup of our platform is much simpler than the angle tuning operational mode of conventional SPR systems, and has great potential for system miniaturization and low-cost production.

IV. INTEGRATION OF THE PIA BIOCHIP WITH A SMART-PHONE-BASED MICROSCOPE SYSTEM

Because of the world-wide cell-phone subscription, mobile medical devices have attracted significant attention to combat global health problems, such as cancer, especially for developing countries and resource-limited areas. It will be very beneficial if we can integrate the highly sensitive and low-cost PIA biochip with the imaging system of smart-phones. Therefore, in this section, we continued to investigate the possibility of detecting exosomal EGFR using a smart-phone-based microscope. As shown in Fig. 4(a), a miniaturized plano-concave lens with a diameter of 1 mm (Edmund) was embedded in a homemade phone-case and aligned with the smart-phone camera (Nokia Lumia 1020), comprising a portable microscopy system with the magnitude of approximately 10X. By adjusting the simple optical system shown in Fig. 4(a), the transmitted light through a 6×6 plasmonic interferometer array was detected by the built-in CMOS camera of the cell phone (Fig. 4(b)). A series of glycerol-water solutions (i.e., 3%, 6%, and 9% glycerol solutions) were first tested on the PIA biochip to quantify its sensitivity and resolution. As shown in Fig. 4(c), after the glycerol solutions were flowed into the PIA biochip, the transmission intensity through the plasmonic interferometer increased with increasing concentration of glycerol solutions. After washing off the biochip with deionized water, the transmission intensity signal returned back to the baseline. Compared with the same PIA biochip characterized using the desktop microscope shown in Fig. 2, we obtained a similar optical response with larger noise due to the intrinsic noise of the built-in CMOS camera. We estimated that the sensitivity and resolution of the



Fig. 4. (a) Proof-of-concept experiment setup of the mobile PIA biochip integrated with the smart-phone imaging system. (b) The screen of the smart-phone (Nokia Lumia 1020) with the PIA biochip transmission image. (c-d) Real-time response of (c) bulk refractive index and (d) surface binding changes measured by the PIA biochip coupled with the smart-phone-based microscope.

PIA biochip coupled with the smart-phone imaging system are $1.35 \times 10^4 \%/\text{RIU}$ and 1.27×10^{-4} RIU, respectively.

Next, we investigated the feasibility of exosomal EGFR detection using the mobile PIA sensing setup. A similar surface treatment procedure was employed to modify the sensor surface with anti-EGFR antibodies. Di-H₂O and PBS solutions were fed into the PIA biochip at flow rate of 0.02 mL/min for 10 minutes and 20 minutes respectively to collect the baseline signals (i.e., I_{water} and I_{PBS}). Then exosomes derived from A549 lung cancer cells were resuspended in PBS at the concentration of 8×10^{10} exosomes/mL and flowed into the PIA biochip at a flow rate of 0.02 mL/min. As shown in Fig. 4(d), similar phenomena were observed through the smart-phonebased PIA sensing system compared with the results obtained using the desktop microscope system (Fig. 3(b)). The expression of exosomal EGFR was calculated as 0.49 using Eq. (2). The SNR of the results obtained by the smart-phone-based system was calculated as 8.23, corresponding to the sensing resolution of 9.72×10^9 exosomes/mL. Although the concentration of exosomes applied in the smart-phone-based PIA sensing system $(8 \times 10^{10} \text{ exosomes/mL})$ was 4 times higher than that of exosomes applied in the desktop microscope system (2×10^{10} exosomes/mL), we only observed 2.33-fold, instead of 4-fold, increase in exosomal EGFR level. The relatively lower sensing performance should be attributed to the limited resolution and noise level of the low-cost smart-phone camera. However, these experimental results successfully demonstrated the feasibility of the mobile PIA biochip in detecting exosomal protein biomarkers for cancer diagnosis. An improved sensing performance is expected if higher performance components are employed in the portable systems, which is also under investigation. For the next step, the clinical utility of the PIA biochip in cancer diagnosis will be further demonstrated using blood samples from cancer patients and normal controls, which is also under investigation. While such devices may not be able to completely replace advanced diagnostics in hospitals, they will provide "early warnings" that will improve the overall early detection of lung cancer and many other types of cancer/diseases, and thus reduce the mortality.

V. CONCLUSION

In conclusion, we reported a highly integrated, portable ringhole PIA biochip, which is a highly sensitive, cost-effective, fast/real-time and label-free optical sensor for specific sensing of biomolecules, such as exosomal proteins. By combining two complementary sensor units, the background fluctuation can be minimized, resulting in the sensing resolution of $\sim 1.63 \times 10^{-6}$ RIU by integrating multiple sensor units signals observed using the desktop microscope. Surface binding of exosomes with the sensing resolution of 3.86×10^8 exosomes/mL and $9.72 \times$ 10⁹ exosomes/mL was successfully realized on the desk-top optical microscope and the smart-phone-based microscope, respectively. The proposed high performance and compact sensor system is critical for overcoming size, cost and detection time barriers of conventional technologies. Compared with conventional prism-based SPR systems, our miniaturized, compact PIA platform does not require angular tunable prism coupling systems, and therefore can be realized with a significant reduction in device cost and instrumental complexity. This smartphonebased, highly sensitive, and low cost PIA biochip is promising for label-free sensing with great impact on point-of-care diagnostics. It can assist in advancing basic cancer research, and serve as a routine pre-screening and rapid diagnostic tool that could complement more invasive and expensive testing and provide additional information for clinical decision making. When combined with wireless communication and signal processing advances, such portable diagnosis tools can be used to construct a global biosensor network to monitor and control the global endemic disease threats. We expect that this mobile biosensing system with PIA biochips will have potentially transformative impact on biosensing, cancer screening and overall health care.

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